Automotive Electricity and Electronics, 6th Edition Quiz 29A	
Name	
MULTIPLE CHOICE. Choose the one alternative that best completes the statement or answers the question	ion.
 Rear cross-traffic alert is used to warn the driver when backing out from a parking space if there is a vehicle approaching from either side. The system uses installed on both sides of the vehicle near the rear bumper. A) Sonar B) Ultrasonic C) Radar D) Cameras 	1)
 2) A typical radar cruise control system uses A) Long range radar (LRR) B) Short range radar (SRR) C) Electronic throttle control system to control vehicle speed D) All of the above 	2)
 3) A radar cruise control system is designed to A) Warn when police radar is present B) Maintain a set distance between vehicles C) Disengage when police radar is detected D) None of the above 	3)
 4) Adaptive cruise control systems can also be called A) Dynamic cruise control B) Active cruise control C) Radar cruise control D) Any of the above 	4)
 5) A driver complains that the brakes seem to release slowly at times, usually when stopped on a hill. This is normal operation of the systems. A) Hill keep assist B) Adaptive cruise control C) Pre-collision systems D) Automatic emergency braking 	5)
6) Self-parking vehicles use and control the to control the vehicle into a parking	6)

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space.

A) Radar; throttle

C) Sonic sensor; brakes

B) Camera; electric power steering

D) Radar; electric power steering

7) A parking-assist system works to warn the driver if the vehicle is getting close to an object. What	7)
type of object CANNOT be detected by most systems?	
A) Objects larger than 3 inches (8 cm) wide	
B) Objects larger than 10 inches (25 cm) high	
C) Objects under the vehicle	
D) Any of the above	
D) They of the above	
8) Calibrating radar and cameras involves all of the following EXCEPT	8)
A) Factory or factory-level scan tool	
B) Special targets set at precisely specified location around the vehicle	
C) Both static (stationary and dynamic (moving) calibration is required	
D) Driving the vehicle in a circle 10 times to calibrate the cameras	
By Briving the verticle in a circle to three to canorate the cameras	
9) What is NOT a function of advanced driver assist systems?	9)
A) Self-drive capability	, <u> </u>
B) Take the load off the driver	
C) Help the driver avoid a collision if a vehicle in front of them stops quickly	
D) Alert the driver of a potential issue	
b) There the driver of a potential issue	
10) The purpose of lane keep assist (LKA) is	10)
A) To warn the driver if moving out of a lane	
B) Used with adaptive cruise control to self-drive the vehicle without driver input or control	
C) To keep the vehicle within the lane, using the electric power steering	
D) Both A and C	

Answer Key

Testname: AEE6_29A

- 1) C
 - Page Ref: 398
- 2) D
- Page Ref: 396-397
- 3) B
 - Page Ref: 396
- 4) D
 - Page Ref: 396
- 5) A
 - Page Ref: 400
- 6) B
 - Page Ref: 395
- 7) D
 - Page Ref: 396
- 8) D
 - Page Ref: 400-401
- 9) B
 - Page Ref: 392
- 10) D
 - Page Ref: 395